

IN THE SPECIFICATION

Please amend the specification under 37 C.F.R. § 1.121(b) as set forth below.

RELATED APPLICATION

1. The present application is a Continuation of U.S. Patent Application, Serial No. 09/714,354, filed on November 16, 2000, entitled *Modular Stamped Parts Transfer Gripper*, which is a Continuation-in-Part of U.S. Patent Application, Serial No. 09/483,794, filed January 14, 2000, entitled *Modular Stamped Parts Transfer Gripper*, (now U.S. Patent No. 6,227,586, issued on May 8, 2001), which is a Continuation of U.S. Patent Application Serial No. 08/981,863, filed on August 4, 1998, entitled *Modular Stamped Parts Transfer Gripper* (now U.S. Patent No. 6,048,013, issued on April 11, 2000), which is related to and claims priority to PCT Application No. US97/17795 (WO98/15392), filed on October 3, 1997, which is related to and claims priority to U.S. Provisional Patent Application, Serial No. 60/039,088, filed March 14, 1997, entitled *Modular Stamped Parts Transfer Gripper*, and to U.S. Provisional Patent Application Serial No. 60/027,668 filed October 7, 1996, entitled *Stamped Parts Transfer Gripper*. To the extent not included below, the subject matter disclosed in those applications is hereby expressly incorporated into the present application.

2. Please replace the paragraph beginning on page 6, line 12, as follows:

Fig. 8 is a partial cross-sectional view of Fig. 6 taken along plane ~~IV-IV~~ VIII-VIII;

3. Please replace the paragraph beginning on page 7, line 14, as follows:

Figs. 26a and 26b are schematic views which depict a modular fluid activated gripper having an upper pivotal gripper jaw 100c and a lower stationary gripper jaw 100i. Fig. 26a is a side view of the modular fluid activated gripper. Fig. ~~51b~~ 26b is a bottom view of the modular fluid activated gripper.

4. Please replace the paragraph beginning on page 17, line 12, as follows:

Fig. 10 depicts a number of different interchangeable gripper jaws 100a to 100i which can be assembled in the body 101 and coupled to the jaw driver assembly 102. As depicted, each of the different jaws 100a to 100i have different tip end designs and/or cam slots ~~100b~~ 103 that effect different movement characteristics. As depicted in Fig. 10 and discussed in more detail below, the modular gripper of the present invention can be assembled to include gripper jaws having different tip designs that can be used for handling, e.g., transporting or transferring, different types of workpieces. Also, as discussed below, the modular gripper can be assembled with gripper jaws 100 having different cam slot 103 configurations which can affect the angle at which one or both jaws open or close, and which determine whether or not the jaws lock in an open and/or closed position.

5. Please replace the paragraph beginning on page 23, line 13, as follows:

Figs. 18a-18d and 19a-19e depict reversible gripper tips 140 which have double cone points 141 and double diamond point pads 142. Fig. 18a is a perspective view of a reversible gripper tip 140. Fig. 18b is a top of view thereof. Fig. 18c is cross sectional view taken along ~~D-D~~ C-C in Fig. 18d. Fig. 18d is a front view of the reversible gripper tip 140.